# AB Allen-Bradley 

Technical Data


PowerFlex ${ }^{(1)}$ 700H High<br>Power<br>Adjustable Frequency AC Drives

## PowerFlex 700H Adjustable Frequency AC Drive Technical Data

The PowerFlex 700H AC drive offers a cost-effective, compact package for general purpose, variable speed applications. It is designed to meet the demands for space, flexibility and performance. The many features allow the user to easily configure the drive for most application needs. Ratings currently available include 200 to 450 HP output at 480V AC input.

An LCD Human Interface Module (also used with the PowerFlex ${ }^{\circledR}$ 70, 700 and 700S) provides multilingual text for startup, metering, programming, and troubleshooting.

PowerFlex 700 H AC drives are configurable for Volts-per-Hertz or Sensorless Vector control modes to meet a wide variety of application needs. This control is housed in a module which is separately removable from the power structure. The control module is the same for all drive ratings, simplifying installation and maintenance for the entire product line. Optional I/O is available as 24 V DC or 115 V AC.

Optional internal communication modules are available as user-installed kits. These provide fast and efficient control and/or data exchange with host controllers over popular interfaces. These interfaces include; DeviceNet ${ }^{\mathrm{TM}}$, ControlNet ${ }^{\text {TM }}$, Ethernet/IP, Profibus, Interbus, Remote I/O, Serial Communications and other open control and communication networks. PC tools such as DriveExplorer ${ }^{\text {TM }}$ and DriveTools ${ }^{\text {TM }}$ SP assist with programming, monitoring and troubleshooting the PowerFlex 700H.

## Table of Contents

Description ..... Page
Catalog Number Explanation .....  4
Option Selection ..... 5
Accessories ..... 8
Power Wiring. ..... 9
Power Terminals ..... 10
Control Terminals ..... 12
Cable Recommendations ..... 18
Mounting ..... 20
Approximate Dimensions ..... 21
Control and Performance Specifications ..... 23
Drive, Fuse \& Circuit Breaker Ratings ..... 24
Parameter List ..... 26

## Flexible Packaging and Mounting

Flexible Programming, Hardware, and Communication Interfaces.

- Advanced features and parameter set modeled after the PowerFlex ${ }^{\circledR} 700$ AC drive.
- Standard I/O includes either 24 V or 115 V digital I/O plus analog I/O.
- NetLinx ${ }^{\mathrm{TM}}$ communication options, including DeviceNet ${ }^{\mathrm{TM}}$, ControlNet ${ }^{\mathrm{TM}}$, and EtherNet/IP networks.


## Easy to Use

- Full-featured LCD Human Interface Module (HIM) with multi-line and multi-lingual display simplifies programming.
- Large and easy to read 7 line x 21 character backlit display
- Variety of languages (English, French, German, Italian, Spanish, Portuguese, Dutch)
- Alternate function keys for shortcuts to common tasks
- "Calculator-like" number pad for fast and easy data entry (Full Numeric version only)
- Control keys for local start, stop, speed, and direction
- Remote versions for panel mount application
- S.M.A.R.T. Start and assisted startup routines in the LCD HIM allow for easy configuring and tuning of the drive.
- Pull-apart control terminal blocks allow for easy wiring and quick disconnect of I/O wiring.
- Easy-to-remove control module is common among all PowerFlex 700 H power ratings.
- Optimized global voltage settings designed to worldwide standards allow quick set-up anywhere in the world.
- PC-based configuration tools include:
- DriveExplorer ${ }^{\mathrm{TM}}$ and DriveExplorer Lite

A simple and flexible "On-line" tool for monitoring and configuration while connected to a drive.

- DriveTools ${ }^{\mathrm{TM}} \mathrm{SP}$

A suite of software tools which provide an intuitive means for programming, troubleshooting and maintaining Allen-Bradley AC \& DC drives.

## Industry-Standard Packaging

- Modular design and high degree of power structure commonality with equivalent PowerFlex® 700S AC drive ratings for reduced spare parts stocking.
- Standard floor-standing cabinet designs (frame 10 and larger) for compact stand-alone drive applications or multidrive lineups.


## Catalog Number Explanation

Position


| $480 \mathrm{~V}, 60 \mathrm{~Hz}$ Input |  |  | $400 \mathrm{~V}, 60 \mathrm{~Hz}$ Input |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Code | Amps | HP - ND (HD) | Code | Amps | kW - ND (HD) |
| 261 | 261 | 200 (150) | 261 | 261 | 132 (110) |
| 300 | 300 | 250 (200) | 300 | 300 | 160 (132) |
| 385 | 385 | 300 (250) | 385 | 385 | 200 (160) |
| 460 | 460 | 350 (300) | 460 | 460 | 250 (200) |
| 500 | 500 | 450 (350) | 500 | 500 | 250 (200) |

(1) Frame 10 \& up only.
(2) Brake IGBT available on Frame 9 drives only.
(3) For use on ungrounded distribution systems (Frame 9 drives only).

## PowerFlex 700H Drives

## 380-500V AC, Three-Phase Drives

| 480V AC Input |  |  |  |  | 380-500V AC Input |  |  |  |  | IP21, NEMA Type 1 | Frame Size |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Output Amps |  |  | Normal Duty HP | Heavy Duty HP | Output Amps |  |  | Normal Duty kW | Heavy Duty kW | Catalog Number 20C... |  |
| Cont. | 1 Min. | 2 Sec. 2 |  |  | Cont. | 1 Min. | 2 Sec. 2 |  |  |  |  |
| 261 (205)(1 | 287 (308) | 410 (410) | 200 | 150 | 261 (205) | 287 (308) | 410 (410) | 132 | 110 | D261A0ANNBNN0 | 9 |
| 300 (245)(1) | 330 (368) | 450 (490) | 250 | 200 | 300 (245) | 330 (368) | 450 (490) | 160 | 132 | D300A0ANNBNN0 | 9 |
| 385 (300) $\mathbf{1}$ | 424 (450) | 600 (600) | 300 | 250 | 385 (300) | 424 (450) | 600 (600) | 200 | 160 | D385A0ANNBNN0 | 10 |
| 460 (385) 1 | 506 (578) | 770 (770) | 350 | 300 | 460 (385) | 506 (578) | 770 (770) | 250 | 200 | D460A0ANNBNN0 | 10 |
| 500 (420)(1) | 550 (630) | 750 (840) | 450 | 350 | 500 (420) | 550 (630) | 750 (840) | 250 | 200 | D500A0ANNBNN0 | 10 |

(1) These drives have dual current ratings; one for normal duty applications, and one for heavy duty applications (in parenthesis). The drive may be operated at either rating.
(2) The 2 sec. output current is only available at initial start or drive operating at light load.

## Product Selection

## Option Selection

## Position 9 - Human Interface Modules (HIM)

Position 9 of the catalog string specifies the Human Interface Module (HIM). Four LCD styles are available as well as a blank plate. These HIMs can be factory or user installed.

| 20C | D | 261 | A | 0 | A | Y | N | B | N | N | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Dive |  | No a | Enolowe | HIM | Amena | Bate | Brate | Enision | Comm Sot | 10 | Feathad |

Default Value "0" - HIM Not Used (Blank Cover Included)
Choose User Installed Kit — Leave Default Value " 0 "
User Installed Kit ©

| Description | Handheld/Local (Drive <br> Mount) Catalog Number |
| :--- | :--- |
| Blank Plate | $20-\mathrm{HIM}-\mathrm{A0}$ |
| LCD Display, Digital Speed | $20-\mathrm{HIM}-\mathrm{A} 2$ |
| LCD Display, Full Numeric Keypad | $20-\mathrm{HIM}-\mathrm{A3}$ |
| LCD Display, Analog Speed Potentiometer | $20-\mathrm{HIM}-\mathrm{A} 4$ |
| LCD Display, Programmer Only | $20-\mathrm{HIM}-\mathrm{A5}$ |

(1) Separately-Mounted HIMs can be found on page 8, Accessories.
(2) For indoor use only.
(3) Includes a 1202-C30 cable ( 30 meters).

Choose Catalog Code- Factory Installed Option
Factory Installed Options


Catalog Code: 0 No HIM (Blank Cover)


Catalog Code: 3 LCD Full Numeric


Catalog Code: C Door Mounted LCD Full Numeric Frame 10 Only

## Position 10 - Documentation

Position 10 specifies documentation. Documentation set includes Programming \& Installation Manuals.

| 20C | $\mathbf{D}$ | $\mathbf{2 6 1}$ | $\mathbf{A}$ | $\mathbf{0}$ | $\mathbf{A}$ | $\mathbf{Y}$ | $\mathbf{N}$ | $\mathbf{B}$ | $\mathbf{N}$ | $\mathbf{N}$ | $\mathbf{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Drive | Voltage <br> Rating | ND Rating | Enclosure | HIM | Documentation | Brake | Brake <br> Resistor | Emission | Comm Slot | I/O | Feedback |

## Product Selection

Option Selection (continued)

## Position 11 - Internal Brake IGBT

Position 11 specifies the Internal Dynamic Brake IGBT.


## Position 12 - Dynamic Brake Resistors

Position 12 specifies the Internal Dynamic Brake resistor which is not available at this time.

| 20C | D | 261 | A | 0 | A | N | N | B | N | N | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Dive | $\substack{\text { Volase } \\ \text { Rating }}$ | No R Rating | Enosure | нм | Documenation | Bake |  | Enision | ${ }^{\text {Comm Sot }}$ | 10 | Feeduad |
| $\square$ Defauliv value "N" - No Dynamic Brake Resistor included $^{\text {a }}$ |  |  |  |  |  |  |  |  |  |  |  |

## Position 13 - EMC Filter

Position 13 identifies the presence of the internal EMC filter (meets second environment CE standards).

(1) Important: For use on ungrounded distribution systems (Frame 9 drives only).

## Product Selection

Option Selection (continued)

## Position 14 - Communication Adapter

Position 14 selects a communications adapter for the drive. Adapters are available for most industrial networks and can be supplied factory installed or as field kits.

| 200 | D | 261 | A | 0 | A | Y | N | $B$ | N | N | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Drive | Voltage Rating | ND Rating | Enclosure | HIM | Documentation | Brake | Brake Resistor | Emission | Comm Slot | I/O | Feedback |


| Default Value "N" — Communication Adapters Not Used |  |
| :--- | :--- |
|  |  |
| Choose User Installed Kit — Leave Default Value "N" |  |
| User Installed Kit | Catalog Number |
| Description | $20-C O M M-C$ |
| ControlNet Communication Adapter | $20-C O M M-D$ |
| DeviceNet Communication Adapter | $20-C O M M-E$ |
| Ethernet/IP Communication Adapter | $20-C O M M-H$ |
| HVAC Communication Adapter | $20-C O M M-I$ |
| Interbus Communication Adapter | $20-C O M M-L$ |
| LonWorks Communication Adapter | $20-C O M M-P$ |
| Profibus Communication Adapter | $20-C O M M-R$ |
| Remote I/O Communication Adapter | $20-C O M M-S$ |
| RS-485 DF1 Communication Adapter | $1203-S N M$ |
| Serial Null Modem Adapter | $1203-S S S$ |
| Smart Self-powered Serial Converter (RS-232) - includes |  |
| 1203-SFC and 1202-C10 Cables |  |

## Position 15 - l/O Option Card

Position 15 specifies I/O voltage.


| Choose User Installed Kit - Leave Default Value "N" |  |
| :---: | :---: |
| Description | Catalog No. |
| 24V DC Digital Input w/Analog I/O | 20C-DA1-A |
| 115V AC Digital Input w/Analog I/O | 20C-DA1-B |
| 115V AC Digital Outputs | 20C-D01 |
| Choose Catalog Code - Factory Installed Option |  |
| Description | Catalog Code |
| 24V DC Digital Input w/Analog I/O and 115V AC Digital Output | A( |
| 115V AC Digital Input w/Analog I/O and 115V AC Digital Output | B( |
| None | N |

Option Selection (continued)

## Position 16 - Input Cards for Feedback Devices

Position 16 specifies the input card for the desired feedback device.


## Accessories

Accessory kits are available to supplement the drive installation or tailor the drive to the particular requirements. These may include installation issues, communications structure or others.

Separately-Mounted Human Interface Module (HIM)

| Description | Remote (Panel Mount) IP 66, UL Type 4x12 © |
| :--- | :--- |
|  | Catalog Number |
|  | 20 HIM-C3 ( |

(1) For indoor use only.
(2) Includes a PowerFlex HIM Interface Cable (20-HIM-H10).

## Human Interface Module Interface Cables

| Description | Catalog Number |
| :---: | :---: |
| Bezel Kit for LCD HIMs, NEMA 1 ( | 20-HIM-B1 |
| PowerFlex HIM Interface Cable, 1 m (39 in.) (2) | 20-HIM-H10 |
| Cable Kit (Male-Female) 3 0.33 Meters (1.1 Feet) <br> 1 Meter (3.3 Feet) <br> 3 Meter ( 9.8 Feet) <br> 9 Meter (29.5 Feet) | $\begin{array}{\|l\|} 1202-\mathrm{H} 03 \\ 1202-\mathrm{H} 10 \\ 1202-\mathrm{H} 30 \\ 1202-\mathrm{H} 90 \end{array}$ |
| DPI/SCANport ${ }^{\text {TM }}$ One to Two Port Splitter Cable | 1203-S03 |

(1) Includes an interface cable (1202-C30) for connection to drive.
(2) Required only when HIM is used as handheld or remote.
(3) Required in addition to 20 -HIM-H10 for distances to a total maximum of 10 Meter ( 32.8 Feet).

## Reflected Wave Reduction

Terminator

| Description © | Used with | Catalog Number <br> (Loose Kit) |
| :--- | :--- | :--- |
| IP65 (NEMA Type4x) | $0.37-1.5 \mathrm{~kW}(0.5-2 \mathrm{HP}) 460 \mathrm{~V}$ Drives | $1204-$ TFA1 |
| Connection Cable Included | $0.75-597 \mathrm{~kW}(1-800 \mathrm{HP}) 575 \mathrm{~V}$ Drives |  |

(1) Correct terminator selection is dependent on motor characteristics, cable type and cable length. Refer to publication 1204-1.0 for application details before ordering.

## Product Selection

## Power Wiring

The PowerFlex 700 H has the following built in protective features to help simplify installation:

- Ground fault protection during start up and running ensures reliable operation
- Electronic motor overload protection increases motor life
- To ensure compatibility with ungrounded systems, Frame 10 drives incorporate removable MOV to ground and common mode capacitors to ground. Frame 9 drives can be specially ordered to allow compatibility with ungrounded systems.
- 6 kV transient protection provides increased robustness for $380-480 \mathrm{~V}$ system voltages

There are many other factors that must be considered for optimal performance in any given application. The block diagram below highlights the primary installation considerations.
DC Input

## Installation Considerations

## Terminals

Terminal Locations - Frame 9


Power Terminal Block


Power Terminal Specifications - Frame 9

| No. | Name | Description | Wire Size Range 183 |  | Torque <br> Recommended |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Maximum | Minimum |  |
| (1) | Input Power Terminal Block L1, L2, L3 | Input power | $\begin{aligned} & 185.0 \mathrm{~mm}^{2} \\ & (350 \mathrm{MCM}) \end{aligned}$ | $\begin{aligned} & 95.0 \mathrm{~mm}^{2} \\ & (4 / 0 \mathrm{AWG}) \end{aligned}$ | $\begin{aligned} & 40 \mathrm{~N}-\mathrm{m} \\ & (354 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |
| (2) | Output Power Terminal Block U/T1, V/T2, W/T3 | Motor connections | $\begin{aligned} & 185.0 \mathrm{~mm}^{2} \\ & (350 \mathrm{MCM}) \end{aligned}$ | $\begin{aligned} & 95.0 \mathrm{~mm}^{2} \\ & (4 / 0 \mathrm{AWG}) \end{aligned}$ | $40 \mathrm{~N}-\mathrm{m}$ ( 354 lb .-in.) |
| (3) | SHLD Terminal, PE, Motor Ground | Terminating point for wiring shields | $\begin{array}{\|l} \hline 95.0 \mathrm{~mm}^{2} \\ \text { (4/0 AWG) } \end{array}$ | $\begin{aligned} & 5.0 \mathrm{~mm} 2 \\ & (10 \mathrm{AWG}) \end{aligned}$ | $\begin{aligned} & 22 \mathrm{~N}-\mathrm{m} \\ & (195 \mathrm{lb} . \mathrm{in} .) \end{aligned}$ |
| (4) | DC Bus 2 <br> (2 Terminals; DC-, DC+) | DC input or external brake (Internal Brake option not ordered) | $\begin{aligned} & 185.0 \mathrm{~mm}^{2} \\ & (350 \mathrm{MCM}) \end{aligned}$ | $\begin{aligned} & 95.0 \mathrm{~mm}^{2} \\ & (4 / 0 \mathrm{AWG}) \end{aligned}$ | $\begin{aligned} & 40 \mathrm{~N}-\mathrm{m} \\ & (354 \mathrm{lb} . \mathrm{in} .) \end{aligned}$ |
|  | DC Bus w/Brake (2 (3 Terminals; DC-, DC+/R+, R-) | DC input/internal brake (Internal Brake option is ordered) | $\begin{aligned} & 185.0 \mathrm{~mm}^{2} \\ & (350 \mathrm{MCM}) \end{aligned}$ | $\begin{aligned} & 95.0 \mathrm{~mm}^{2} \\ & \text { (4/0 AWG) } \end{aligned}$ | $\begin{aligned} & 40 \mathrm{~N}-\mathrm{m} \\ & (354 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ |

(5)

Cable Clamp for Strain Relief
(1) Do Not exceed maximum wire size. Parallel connections may be required.
(2) DC terminal and brake lugs can be removed.
(3) Maximum/minimum sizes that the terminal block will accept - these are not recommendations.

## Installation Considerations

## Terminals (continued)

Terminal Locations - Frame 10


Power Terminal Specifications - Frame 10

| No. | Name | Description | Wire Size Range (12 |  | Torque | $\begin{aligned} & \text { Terminal Bolt } \\ & \text { Size } \mathbf{3 4} \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Maximum | Minimum | Recommended |  |
| (1) | Input Power Terminal Block(3 L1, L2, L3 | Input power | $\begin{aligned} & 300 \mathrm{~mm}^{2} \\ & (600 \mathrm{MCM}) \end{aligned}$ | $\begin{aligned} & 2.1 \mathrm{~mm}^{2} \\ & \text { (14 AWG) } \end{aligned}$ | $\begin{aligned} & 40 \mathrm{~N}-\mathrm{m} \\ & (354 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ | M12 |
| (2) | Output Power Terminal Block(3 U/T1, V/T2, W/T3 | Motor connections | $\begin{aligned} & 300 \mathrm{~mm}^{2} \\ & (600 \mathrm{MCM}) \end{aligned}$ | $\begin{aligned} & 2.1 \mathrm{~mm}^{2} \\ & (14 \mathrm{AWG}) \end{aligned}$ | $\begin{aligned} & 40 \mathrm{~N}-\mathrm{m} \\ & (354 \mathrm{lb} .-\mathrm{in} .) \end{aligned}$ | M12 |
| (3) | SHLD Terminal, PE, Motor Ground 3 | Terminating point for wiring shields | $\begin{array}{\|l\|} \hline 300 \mathrm{~mm}^{2} \\ (600 \mathrm{MCM}) \end{array}$ | $\begin{aligned} & \hline 2.1 \mathrm{~mm}^{2} \\ & \text { (14 AWG) } \\ & \hline \end{aligned}$ | $\begin{aligned} & 40 \mathrm{~N}-\mathrm{m} \\ & (354 \mathrm{lb} . \mathrm{in} .) \end{aligned}$ | M10 |
| (4) | DC Bus 3 <br> (2 Terminals; DC-, DC+) | DC input or external brake (Internal Brake option not ordered) | $\begin{aligned} & 300 \mathrm{~mm}^{2} \\ & (600 \mathrm{MCM}) \end{aligned}$ | $\begin{aligned} & \hline 2.1 \mathrm{~mm} 2 \\ & (14 \mathrm{AWG}) \end{aligned}$ | $\begin{aligned} & 40 \mathrm{~N}-\mathrm{m} \\ & (354 \mathrm{lb} . \mathrm{in} .) \end{aligned}$ | M12 |
|  | DC Bus w/Brake 3 <br> (3 Terminals; DC-, DC+/R+, R-) | DC input/internal brake (Internal Brake option is ordered) | $\begin{array}{\|l\|} \hline 300 \mathrm{~mm}^{2} \\ (600 \mathrm{MCM}) \end{array}$ | $\begin{aligned} & 2.1 \mathrm{~mm}^{2} \\ & \text { (14 AWG) } \end{aligned}$ | $\begin{aligned} & 40 \mathrm{~N}-\mathrm{m} \\ & (354 \mathrm{lb} . \mathrm{in} .) \end{aligned}$ | M12 |

(5) Cable Clamp for Strain Relief
(1) Maximum/minimum sizes that the terminal block will accept - these are not recommendations
(2) Do Not exceed maximum wire size. Parallel connections may be required.
(3) These connections are bus bar type terminations and require the use of lug type connectors.
(4) Apply counter torque to the nut on the other side of terminations when tightening or loosening the terminal bolt in order to avoid damage to the terminal.

## Installation Considerations

## Control Terminals

## I/O Terminal Blocks \& Jumpers



I/O Terminal Block Specifications

| No. | Name | Description | Wire Size Range ${ }^{\text {c }}$ |  | Torque |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Maximum | Minimum | Maximum | Recommended |
| (1) | Analog I/O | Analog I/O Signals | $\begin{aligned} & 2.5 \mathrm{~mm}^{2} \\ & (14 \mathrm{AWG}) \end{aligned}$ | $\begin{aligned} & 0.5 \mathrm{~mm}^{2} \\ & (22 \mathrm{AWG}) \end{aligned}$ | $\begin{aligned} & \text { 0.2 N-m } \\ & 1.8 \mathrm{lb} .-\mathrm{in} . \end{aligned}$ | $\begin{aligned} & 0.2 \mathrm{~N}-\mathrm{m} \\ & 1.8 \mathrm{lb} . \mathrm{in} . \end{aligned}$ |
| (2) | Digital Inputs | Digital Input Signals | $\begin{aligned} & 2.5 \mathrm{~mm}^{2} \\ & \text { (14 AWG) } \end{aligned}$ | $\begin{aligned} & 0.5 \mathrm{~mm}^{2} \\ & (22 \mathrm{AWG}) \end{aligned}$ | $\begin{aligned} & \text { 0.2 N-m } \\ & 1.8 \mathrm{lb} .-\mathrm{in} . \end{aligned}$ | $\begin{aligned} & 0.2 \mathrm{~N}-\mathrm{m} \\ & 1.8 \mathrm{lb} .-\mathrm{in} . \end{aligned}$ |
| (3) | Digital Outputs | Digital Out Relays | $\begin{aligned} & 2.5 \mathrm{~mm}^{2} \\ & (14 \mathrm{AWG}) \\ & \hline \end{aligned}$ | $\begin{aligned} & 0.5 \mathrm{~mm}^{2} \\ & (22 \mathrm{AWG}) \end{aligned}$ | $\begin{aligned} & 0.5 \mathrm{~N}-\mathrm{m} \\ & 4.5 \mathrm{lb} .-\mathrm{in} . \end{aligned}$ | $\begin{aligned} & 0.5 \mathrm{~N}-\mathrm{m} \\ & 4.5 \mathrm{lb} . \mathrm{in} . \end{aligned}$ |

(1) Maximum/minimum sizes that the terminal block will accept - these are not recommendations.

## Installation Considerations

## Control Terminals (continued)

## I/O Terminal Designations

|  | No. | Signal |  | Description |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 | Analog $\ln 1(-) \mathbf{1}$ | 4 | Isolated ©, bipolar, differential, 9 bit \& sign, 88k ohm input impedance. A jumper (page 14) selects: $0-10 \mathrm{~V}, \pm 10 \mathrm{~V}, 4-20 \mathrm{~mA}$. Default: 0-10V (Ri=200k), 4-20mA (Ri=100 ohm). | $\begin{aligned} & 320- \\ & 327 \end{aligned}$ |
|  | 2 | Analog $\ln 1(+)$ (1) |  |  |  |
|  | 3 | Analog $\ln 2(-) \mathbf{1}$ |  |  |  |
|  | 4 | Analog $\ln 2(+)$ (1) |  |  |  |
|  | 5 | -10V Pot Reference | - | 2k ohm minimum, 10 mA maximum load, 1\% accuracy. |  |
|  | 6 | Pot Common (GND) |  | For (+) and (-) 10V pot references. |  |
|  | 7 | +10V Pot Reference | - | 2 k ohm minimum, 10 mA maximum load, $1 \%$ accuracy. |  |
|  | 8 | Analog Out 1 (+) | 4 | Bipolar (current out is not bipolar), 9 bit \& sign, 2 k ohm minimum load. A jumper (see page 14) selects: $0-10 \mathrm{~V}, \pm 10 \mathrm{~V}, 4-20 \mathrm{~mA}$. | $\begin{aligned} & 340- \\ & 347 \end{aligned}$ |
|  | 9 | Analog Out Common |  |  |  |
|  | 10 | Analog Out 2 (+) |  |  |  |
|  | 11 | Digital In 1 | Stop - CF | 115 V AC, $50 / 60 \mathrm{~Hz}$ - Opto isolated <br> Low State: less than 30V AC <br> High State: greater than 40V AC <br> 24V DC - Opto isolated (250V) <br> Low State: less than 5V DC <br> High State: greater than 20V DC <br> 11.2 mA DC <br> Enable: Digital Input 6 is jumper selectable for HW Enable. <br> On-Time: < 16.7ms, Off-Time < 1 ms | $\begin{aligned} & 361- \\ & 366 \end{aligned}$ |
|  | 12 | Digital In 2 | Start |  |  |
|  | 13 | Digital In 3 | Jog |  |  |
|  | 14 | Digital In 4 | Speed Sel 1 |  |  |
|  | 15 | Digital In 5 | Speed Sel 2 |  |  |
|  | 16 | Digital In 6/Hardware Enable, see pg. 15 | Speed Sel 3 |  |  |
|  | $\begin{aligned} & 17 \\ & 18 \end{aligned}$ | Digital In Common |  | Allows source or sink operation. Terminals 17/18 \& 19 can also be used to provide backup power to DPI and control devices. |  |
|  | 19 | +24VDC 0 | - | Drive supplied logic input power. |  |
|  | 20 | 24 V Common 2 | - | Common for internal power supply. |  |
|  | 21 | Digital Out 1 - N.C. ${ }^{\text {c }}$ | Fault | Max. Resistive Load: 240V AC/30V DC - 1200VA, 150W Max. Current: 5A, Min. Load: 10mA Max. Inductive Load: 240V AC/30V DC - 840VA, 105W Max. Current: 3.5A, Min. Load: 10 mA | $\begin{array}{\|l\|} \hline 380 \\ 391 \end{array}$ |
|  | 22 | Digital Out 1 Common |  |  |  |
|  | 23 | Digital Out 1 - N.O. 3 | NOT Fault |  |  |
|  | 24 | Digital Out 2 - N.C. 3 | NOT Run |  |  |
|  | 25 | Digital Out 2/3 Com. |  |  |  |
|  | 26 | Digital Out 3-N.O. 3 | Run |  |  |

(1) Important: Input must be configured with a jumper. Drive damage may occur if jumper is not installed properly. Refer to page 14.
(2) 150 mA maximum Load. Not present on 115 V versions. Can be used to provide control power from an external 24 V source when main power is not applied. Refer to page 15.
(3) Contacts in unpowered state. Any relay programmed as Fault or Alarm will energize (pick up) when power is applied to drive and deenergize (drop out) when a fault or alarm exists. Relays selected for other functions will energize only when that condition exists and will deenergize when condition is removed.
(4) These inputs/outputs are dependant on a number of parameters (see "Related Parameters").
(5) Differential Isolation - External source must be maintained at less than 160 V with respect to PE . Input provides high common mode immunity

## Installation Considerations

## I/O Cable Grounding

When installing/stripping shielded multi-conductor cable for analog and digital I/O, allow sufficient distance from the terminal plug to permit attachment to the cable clamp for grounding and strain relief.


## Analog I/O Configuration

Important: Analog I/O must be configured through programming, as well as the jumpers shown below.
//O Configuration

| Signal | Jumper | Setting |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Analog Inputs | $\begin{aligned} & \mathrm{J} 1(\text { Analog } \ln 1) \\ & \mathrm{J} 2(\text { Analog } \ln 2) \end{aligned}$ | 0-20 mA | 0-10V | $\pm 10 \mathrm{~V}$ |  |
|  |  |  |  | $\begin{aligned} & \frac{J 1}{\text { AB B C }} \\ & \text { OOOO OO } \\ & 0000 \end{aligned}$ |  |
| Analog | J3 (Analog Out 1) | 0-20 mA | 0-10V | $\pm 10 \mathrm{~V}$ |  |
|  |  |  |  | $\begin{aligned} & \frac{\mathrm{J3}}{\text { A B C D }} \\ & \text { OOOO } \\ & \text { OOOD } \end{aligned}$ | $\begin{aligned} & \frac{\mathrm{J4}}{\text { A BCD }} \\ & \text { OOOO OO } \\ & 0000 \end{aligned}$ |

## Installation Considerations

## Hardware Enable Circuitry

By default, the user can program a digital input as an Enable input. The status of this input is interpreted by drive software. If the application requires the drive to be disabled without software interpretation, a "dedicated" hardware enable configuration can be utilized. This is done by removing jumper J5 and wiring the enable input to "Digital In 6" (see below). Verify that [Digital In6 Sel], parameter 366 is set to " 1 , Enable."

Hardware Enable Configuration

| Signal | Jumper | Setting |  |
| :--- | :--- | :--- | :--- |
| Hardware <br> Enable | J5 | Hardware Enable | Input Programmable (No Hardware Enable) |
|  |  | $\frac{\mathrm{J} 5}{A B}$ | $\frac{\mathrm{~J}}{}$ |
|  |  | $O O$ | AB |
|  |  |  | 00 |

## Auxiliary Power Supply

You may use an auxiliary power supply to keep the PowerFlex 700H Control Unit energized, when input power is deenergized. This provides back-up power for the Control Unit and is sufficient for setting parameters. Connect 24V DC power to pin 19 and 24 V DC common to pin 20 of the 24 V DC version of the I/O card.

Auxiliary Power Supply Specifications

| Voltage | Current (Min) | Current (Max) |
| :--- | :--- | :--- |
| 24 V DC $\pm 15 \%$ | 150 mA | 250 mA |

If 24 V terminals of several drives are connected in parallel, we recommend using a diode circuit to block current flow in the opposite direction. Reverse current flow could damage the Control Board.


## Installation Considerations

## I/O Wiring Examples

| Input/Output | Connection Example | Required Parameter Changes |
| :---: | :---: | :---: |
| Potentiometer Unipolar Speed Reference ${ }^{0}$ <br> 10k Ohm Pot. <br> Recommended (2k Ohm Minimum) |  | - Adjust Scaling: Parameters 91/92 and 325/326 <br> - View Results: Parameter 002 |
| Joystick Bipolar Speed Reference ${ }^{\boldsymbol{O}}$ $\pm 10 \mathrm{~V}$ Input |  | - Set Direction Mode: <br> Parameter 190 = "1, Bipolar" <br> - Adjust Scaling: Parameters 91/92 and 325/326 <br> - View Results: Parameter 002 |
| Analog Input Bipolar Speed Reference $\pm 10 \mathrm{~V}$ Input |  | - Set Direction Mode: <br> Parameter 190 = "1, Bipolar" <br> - Adjust Scaling: <br> Parameters 91/92 and 325/326 <br> - View Results: <br> Parameter 002 |
| Analog Voltage Input <br> Unipolar Speed <br> Reference <br> 0 to +10V Input |  | - Configure Input with parameter 320 <br> - Adjust Scaling: <br> Parameters 91/92 and 325/326 <br> - View results: <br> Parameter 002 |
| Analog Current Input <br> Unipolar Speed <br> Reference <br> 4-20 mA Input |  | - Configure Input for Current: Parameter 320 and add jumper at appropriate terminals <br> - Adjust Scaling: Parameters $91 / 92$ and $325 / 326$ <br> - View results: Parameter 002 |
| Analog Input, PTC <br> PTC OT set > 5V <br> PTC OT cleared < 4V <br> PTC Short < 0.2V |  | - Set Drive Alarm 1: <br> Parameter 211, bit 11 = "True" <br> - Set Fault Config 1: <br> Parameter 238, bit 7 = "Enabled" <br> - Set Alarm Config 1: <br> Parameter 259, bit 11 = "Enabled" |
| Analog Output <br> $\pm 10 \mathrm{~V}, 4-20 \mathrm{~mA}$ Bipolar <br> +10V Unipolar <br> (shown) |  | - Configure with Parameter 340 <br> - Select Source Value: <br> Parameter 384, [Digital Out1 Sel] <br> - Adjust Scaling: <br> Parameters 343/344 |
| 2-Wire Control NonReversing ${ }^{(2}$ <br> 24V DC internal supply |  | - Disable Digital Input:\#1: <br> Parameter 361 = " 0 , Unused" <br> - Set Digital Input \#2: <br> Parameter 362 = "7, Run" <br> - Set Direction Mode: <br> Parameter 190 = "0, Unipolar" |

[^0]
## Installation Considerations

## I/O Wiring Examples (continued)


(1) Important: Programming inputs for 2 wire control deactivates all HIM Start buttons.

## Cable Recommendations

Important points to remember about I/O wiring:

- Always use copper wire.
- Wire with an insulation rating of 600 V or greater is recommended.
- Control and signal wires should be separated from power wires by at least 0.3 meters ( 1 foot).

Important: I/O terminals labeled " $(-)$ " or "Common" are not referenced to earth ground and are designed to greatly reduce common mode interference. Grounding these terminals can cause signal noise.

## Signal and Control Wire Types

Recommended Signal Wire

| Signal Type | Wire Type(s) | Description | Minimum Insulation Rating |
| :--- | :--- | :--- | :--- |
| Analog I/O | Belden $8760 / 9460$ (or equiv.) | $0.750 \mathrm{~mm}^{2}(18 \mathrm{AWG})$, twisted pair, $100 \%$ shield with drain. $\mathbf{1}$ | $300 \mathrm{~V}, 75-90$ degrees C |
|  | Belden 8770 (or equiv.) | $0.750 \mathrm{~mm}^{2}(18 \mathrm{AWG}), 3$ cond., shielded for remote pot only. | $(167-194$ degrees F$)$ |
| EMC Compliance | Refer to Installation Manual for details. |  |  |
| $\boldsymbol{1}$ If the wires are short and contained within a cabinet which has no sensitive circuits, the use of shielded wire may not be necessary, but is always recommended. |  |  |  |

Recommended Control Wire for Digital I/O

| Type | Wire Type(s) |  | Minimum Insulation <br> Rating |
| :--- | :--- | :--- | :--- |
| Unshielded | Per US NEC or applicable national or local code | Description | $300 \mathrm{~V}, 60$ degrees C |
| Shielded | Multi-conductor shielded cable such as Belden 8770 (or equiv.) | $0.750 \mathrm{~mm}^{2}$ (18AWG), 3 conductor, shielded. | (140 degrees F) |

## Cable Types Acceptable for 200-600 Volt Installations

A variety of cable types are acceptable for drive installations. For many installations, unshielded cable is adequate, provided it can be separated from sensitive circuits. As an approximate guide, allow a spacing of 0.3 meters ( 1 foot) for every 10 meters ( 32.8 feet) of length. In all cases, long parallel runs must be avoided. Do not use cable with an insulation thickness less than or equal to $15 \mathrm{mils}(0.4 \mathrm{~mm} / 0.015 \mathrm{in}$.). Use Copper wire only. Wire gauge requirements and recommendations are based on 75 degrees C. Do not reduce wire gauge when using higher temperature wire.

## Unshielded Cable

THHN, THWN or similar wire is acceptable for drive installation in dry environments provided adequate free air space and/or conduit fill rates limits are provided. Do not use THHN or similarly coated wire in wet areas. Any wire chosen must have a minimum insulation thickness of $15 \mathrm{mils}(0.4 \mathrm{~mm} / 0.015 \mathrm{in}$.) and should not have large variations in insulation concentricity.

## Shielded Cable

Shielded cable contains all of the general benefits of multi-conductor cable with the added benefit of a copper braided shield that can contain much of the noise generated by a typical AC drive. Strong consideration for shielded cable should be given in installations with sensitive equipment such as weigh scales, capacitive proximity switches and other devices that may be affected by electrical noise in the distribution system. Applications with large numbers of drives in a similar location, imposed EMC regulations or a high degree of communications/ networking are also good candidates for shielded cable.

## Cable Recommendations (continued)

Shielded cable may also help reduce shaft voltage and induced bearing currents for some applications. In addition, the increased impedance of shielded cable may help extend the distance that the motor can be located from the drive without the addition of motor protective devices such as terminator networks. Refer to Reflected Wave in "Wiring and Grounding Guidelines for PWM AC Drives," publication DRIVES-IN001A-EN-P.

Consideration should be given to all of the general specifications dictated by the environment of the installation, including temperature, flexibility, moisture characteristics and chemical resistance. In addition, a braided shield should be included and be specified by the cable manufacturer as having coverage of at least $75 \%$. An additional foil shield can greatly improve noise containment.

A good example of recommended cable is Belden® 295xx (xx determines gauge). This cable has four (4) XLPE insulated conductors with a $100 \%$ coverage foil and an $85 \%$ coverage copper braided shield (with drain wire) surrounded by a PVC jacket.

Other types of shielded cable are available, but the selection of these types may limit the allowable cable length. Particularly, some of the newer cables twist 4 conductors of THHN wire and wrap them tightly with a foil shield. This construction can greatly increase the cable charging current required and reduce the overall drive performance. Unless specified in the individual distance tables as tested with the drive, these cables are not recommended and their performance against the lead length limits supplied is not known.

## Armored Cable

Cable with continuous aluminum armor is often recommended in drive system applications or specific industries. It offers most of the advantages of standard shielded cable and also combines considerable mechanical strength and resistance to moisture. It can be installed in concealed and exposed manners and removes the requirement for conduit (EMT) in the installation. It can also be directly buried or embedded in concrete.

Because noise containment can be affected by incidental grounding of the armor to building steel when the cable is mounted, it is recommended the armored cable have an overall PVC jacket. Refer to "Wire Types," in publication DRIVES-IN001, Wiring and Grounding Guidelines for Pulse Width Modulated (PWM) AC Drives.

Interlocked armor is acceptable for shorter cable runs, but continuous welded armor is preferred.
Best performance is achieved with 3 spaced ground conductors, but acceptable performance below 200 HP is provided via a single ground conductor.

Recommended Shielded / Armored Cable

| Location | Rating/Type | Description |
| :---: | :---: | :---: |
| Standard (Option 1) | $600 \mathrm{~V}, 90^{\circ} \mathrm{C}\left(194^{\circ} \mathrm{F}\right)$ <br> XHHW2/RHW-2 <br> Anixter B209500-B209507, Belden 29501-29507, or equivalent | - Four tinned copper conductors with XLPE insulation. <br> - Copper braid/aluminum foil combination shield and tinned copper drain wire. <br> - PVC jacket. |
| Standard (Option 2) | Tray rated 600V, $90^{\circ} \mathrm{C}\left(194^{\circ} \mathrm{F}\right)$ RHH/RHW-2 Anixter OLF-7xxxxx or equivalent | - Three tinned copper conductors with XLPE insulation. <br> - 5 mil single helical copper tape ( $25 \%$ overlap min.) with three bare copper grounds in contact with shield. <br> - PVC jacket. |
| Class I \& II; Division I \& II | Tray rated 600V, $90^{\circ} \mathrm{C}\left(194^{\circ} \mathrm{F}\right)$ RHH/RHW-2 Anixter 7V-7xxxx-3G or equivalent | - Three bare copper conductors with XLPE insulation and impervious corrugated continuously welded aluminum armor. <br> - Black sunlight resistant PVC jacket overall. <br> - Three copper grounds on \#10 AWG and smaller. |

## Installation Considerations

## Mounting

Frame 9


Frame 10


## Operating Temperatures

Drive requires a minimum of $1300 \mathrm{~m}^{3} / \mathrm{h}$ ( 765 cfm ) of cooling air.

| Maximum Surrounding Air Temperature |  |
| :--- | :--- |
| Normal Duty | Heavy Duty |
| 0 to 40 degrees C (32 to 104 degrees F) | 0 to 50 degrees C (32 to 122 degrees F) |

## Approximate Dimensions

Frame 9 Dimensions



Dimensions are in millimeters and (inches).

| Weight kg (lbs.) |  |
| :--- | :--- |
| Drive | Drive \& Packaging |
| 142.9 (315) | 176.9 (390) |

## Installation Considerations

## Approximate Dimensions (continued)

Frame 10 Dimensions


Dimensions are in millimeters and (inches)

| Weight kg (lbs.) |  |
| :--- | :--- |
| Drive | Drive \& Packaging |
| 432 (950) | 447 (985) |

## Control and Performance

| Category |  | PowerFlex 700H |
| :---: | :---: | :---: |
| Agency Certification | (1) | Listed to UL508C and CAN/CSA-C2.2 No. 14-M91. |
|  | $C$ | Marked for all applicable European Directives(1) <br> EMC Directive (89/336/EEC) <br> EN 61800-3 Adjustable Speed electrical power drive systems Low Voltage Directive (73/23/EEC) <br> EN 50178 Electronic Equipment for use in Power Installations |
|  |  | The drive is also designed to meet the following specifications: <br> NFPA 70 - US National Electrical Code <br> NEMA ICS 3.1 - Safety standards for Construction and Guide for Selection, Installation and Operation of Adjustable Speed Drive Systems. IEC 146 - International Electrical Code. |

(1) Applied noise impulses may be counted in addition to the standard pulse train causing erroneously high [Pulse Freq] readings

| Category | Specification | PowerFlex 700H |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Protection | Drive | 380/400 | 480V | 500V | 600 V | 690 V |
|  | AC Input Overvoltage Trip: | 611 V AC | 611V AC | 611V AC | 806 V AC | 806V AC |
|  | AC Input Undervoltage Trip: | 235 V AC | 235 V AC | 235 V AC | 326V AC | 326 V AC |
|  | Bus Overvoltage Trip: | 911V DC | 911V DC | 911V DC | 1200V DC | 1200 V DC |
|  | Bus Undervoltage Shutoff/Fault: | 333 V DC | 333 V DC | 333 V DC | 461V DC | 461V DC |
|  | Nominal Bus Voltage (Full Load): | 517V DC | 621 V DC | 645 V DC | 776V DC | 890V DC |
|  | Heat Sink Thermistor: | Monitored by microprocessor overtemp trip |  |  |  |  |
|  | Drive Overcurrent Trip Software Overcurrent Trip: | - |  |  |  |  |
|  | Hardware Overcurrent Trip: Instantaneous Current Limit: | $360 \%$ of rated heavy duty current (typical) - |  |  |  |  |
|  | Line transients: | up to 6000 volts peak per IEEE C62.41-1991 |  |  |  |  |
|  | Control Logic Noise Immunity: | Showering arc transients up to 1500 V peak |  |  |  |  |
|  | Power Ride-Thru: | 15 milliseconds at full load |  |  |  |  |
|  | Logic Control Ride-Thru: | 0.5 seconds minimum, 2 seconds typical |  |  |  |  |
|  | Ground Fault Trip: | Phase-to-ground on drive output |  |  |  |  |
|  | Short Circuit Trip: | Phase-to-phase on drive output |  |  |  |  |
| Environment | Altitude: | 1000 m (3300 ft) max. without derating |  |  |  |  |
|  | Maximum Surrounding Air Temperature without Derating: | Based on drive rating |  |  |  |  |
|  | Storage Temperature (all const.): | -40 to 60 degrees C (-40 to 140 degrees F) |  |  |  |  |
|  | Atmosphere: | Important: Drive must not be installed in an area where the ambient atmosphere contains volatile or corrosive gas, vapors or dust. If the drive is not going to be installed for a period of time, it must be stored in an area where it will not be exposed to a corrosive atmosphere. |  |  |  |  |
|  | Relative Humidity: | 5 to 95\% non-condensing |  |  |  |  |
|  | Shock: | 15 G peak for $11 \mathrm{~ms} \mathrm{duration} \mathrm{( } \pm 1.0 \mathrm{~ms}$ ) |  |  |  |  |
|  | Vibration: | 2.0 mm (0.0787 in.) displacement, 1G peak EN50178/EN60068-2-6 |  |  |  |  |
| Electrical | Voltage Tolerance: | - |  |  |  |  |
|  | Frequency Tolerance: | $47-63 \mathrm{~Hz}$. |  |  |  |  |
|  | Input Phases: | Three-phase input provides full rating for all drives. Single-phase operation provides $50 \%$ of rated current. |  |  |  |  |
|  | Displacement Power Factor: | 0.98 across entire speed range. |  |  |  |  |
|  | Efficiency: | 97.5\% at rated amps, nominal line volts. |  |  |  |  |
|  | Maximum Short Circuit Rating: | 200,000 Amps symmetrical. |  |  |  |  |
|  | Actual Short Circuit Rating: | Determined by AIC rating of installed fuse/circuit breaker. |  |  |  |  |
|  | Maximum Drive to Motor Power Ratio | Recommended not greater than $2: 1$ ratio. |  |  |  |  |


| Category | Specification | PowerFlex 700H |
| :---: | :---: | :---: |
| Control | Method: | Sine coded PWM with programmable carrier frequency. Ratings apply to all drives (refer to the Derating Guidelines in the PowerFlex Reference Manual). The drive can be supplied as 6 pulse or 12 pulse in a configured package. |
|  | Carrier Frequency: | Minimum: 1 kHz , Maximum: Dependent on drive rating |
|  | Output Voltage Range: | 0 to rated motor voltage |
|  | Output Frequency Range: | 0 to 320 Hz |
|  | $\begin{aligned} & \text { Frequency Accuracy } \\ & \text { Digital Input: } \\ & \text { Analog Input: } \end{aligned}$ | Within $\pm 0.01 \%$ of set output frequency. Within $\pm 0.4 \%$ of maximum output frequency. |
|  | Frequency Control: | Speed regulation - with Slip Compensation $0.5 \%$ of base speed across $40: 1$ speed range 40:1 operating range |
|  | Selectable Motor Control: | Sensorless Vector with full tuning. Standard V/Hz with full custom capability. |
|  | Stop Modes: | Multiple programmable stop modes including - Ramp, Coast, DC-Brake, Ramp-to-Hold and S-curve. |
|  | Accel/Decel: | Two independently programmable accel and decel times. Each time may be programmed from 0 to 3276.7 seconds in 0.1 second increments. |
|  | S-Curve Time | 0-100\% of accel/decel time. |
|  | Intermittent Overload: | $110 \%$ Overload capability for up to 1 minute $150 \%$ Overload capability for up to 2 seconds |
|  | Current Limit Capability: | Proactive Current Limit programmable from 20 to 160\% of rated output current. Programmable proportional gain. |
|  | Electronic Motor Overload Protection: | Class 10 protection with speed sensitive response. Investigated by U.L. to comply with N.E.C. Article 430. U.L. File E59272, volume 12. |

## Drive, Fuse \& Circuit Breaker Ratings

The tables on page 25 provide drive ratings (including continuous, 1 minute $\& 2$ second) and recommended AC line input fuse and circuit breaker information. Both types of short circuit protection are acceptable for UL and IEC requirements. Sizes listed are the recommended sizes based on 40 degree $\underline{C}$ and the U.S. N.E.C. Other country, state or local codes may require different ratings.

## Fusing

If fuses are chosen as the desired protection method, refer to the recommended types listed below. If available amp ratings do not match the tables provided, the closest fuse rating that exceeds the drive rating should be chosen.

- IEC - BS88 (British Standard) Parts $1 \& 2^{*}$, EN60269-1, Parts $1 \& 2$, type gG or equivalent should be used.
- UL - UL Class T, J or L must be used.
* Typical designations include, but may not be limited to the following; Parts 1 \& 2: $A C, A D, B C, B D, C D, D D, E D, E F S, E F, F F, F G, G F, G G, G H$.


## Circuit Breakers

The "non-fuse" listings in the following tables include both circuit breakers (inverse time or instantaneous trip). If one of these is chosen as the desired protection method, the following requirements apply.

- IEC and UL - Both types of devices are acceptable for IEC and UL installations.


## Specifications

400/480 Volt AC Input Protection Devices

| Drive Catalog Number |  | HP Rating |  | Input Ratings |  | Output Amps |  |  | Dual Element Time Delay Fuse |  | Non-Time Delay Fuse |  | $\begin{array}{\|l\|} \hline \text { Circuit } \\ \text { Breaker © } \end{array}$ | Motor Circuit Protector (2) Max.© |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | ND | HD | Amps | kVA | Cont. | 1 Min. | 2 Sec. | Min. 3 | Max. 4 | Min. 3 | Max. 4 |  |  |
| 400 Volt AC Input |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 20xC261 | 9 | 132 | - | 256 | 171 | 261 | 287 | 410 | 325 | 575 | 325 | 700 | 700 | 400 |
|  |  | - | 110 | 201 | 139 | 205 | 308 | 410 | 250 | 450 | 250 | 550 | 600 | 400 |
| $20 x C 300$ | 9 | 160 | - | 294 | 204 | 300 | 330 | 450 | 375 | 800 | 375 | 800 | 800 | 400 |
|  |  | - | 132 | 240 | 166 | 245 | 368 | 490 | 325 | 650 | 325 | 650 | 700 | 400 |
| 20xC385 | 10 | 200 | - | 377 | 261 | 385 | 424 | 600 | 500 | 850 | 500 | 1000 | 800 | 600 |
|  |  | - | 160 | 294 | 204 | 300 | 450 | 600 | 375 | 675 | 375 | 800 | 800 | 400 |
| 20xC460 | 10 | 250 | - | 451 | 312 | 460 | 506 | 770 | 575 | 1000 | 575 | 1200 | 1200 | 600 |
|  |  | - | 200 | 377 | 261 | 385 | 578 | 770 | 500 | 850 | 500 | 1000 | 800 | 600 |
| $20 \times C 500$ | 10 | 250 | - | 490 | 339 | 500 | 550 | 750 | 625 | 1100 | 625 | 1400 | 1200 | 800 |
|  |  | - | 200 | 411 | 285 | 420 | 630 | 840 | 525 | 900 | 525 | 1000 | 1200 | 600 |
| 480 Volt AC Input |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 20xD261 | 9 | 200 | - | 245 | 204 | 261 | 287 | 410 | 325 | 575 | 325 | 700 | 700 | 400 |
|  |  | - | 150 | 193 | 160 | 205 | 308 | 410 | 250 | 450 | 250 | 550 | 600 | 400 |
| 20xD300 | 9 | 250 | - | 282 | 234 | 300 | 330 | 450 | 375 | 800 | 375 | 800 | 800 | 400 |
|  |  | - | 200 | 230 | 191 | 245 | 368 | 490 | 325 | 650 | 325 | 650 | 700 | 400 |
| 20xD385 | 10 | 300 | - | 362 | 301 | 385 | 424 | 600 | 500 | 850 | 500 | 1000 | 800 | 600 |
|  |  | - | 250 | 282 | 234 | 300 | 450 | 600 | 375 | 675 | 375 | 800 | 800 | 400 |
| 20xD460 | 10 | 350 | - | 432 | 359 | 460 | 506 | 770 | 575 | 1000 | 575 | 1200 | 1200 | 600 |
|  |  | - | 300 | 362 | 301 | 385 | 578 | 770 | 500 | 850 | 500 | 1000 | 800 | 600 |
| 20xD500 | 10 | 450 | - | 469 | 390 | 500 | 550 | 750 | 625 | 1100 | 625 | 1400 | 1200 | 800 |
|  |  | - | 350 | 394 | 328 | 420 | 630 | 840 | 525 | 900 | 525 | 1000 | 1200 | 600 |

(1) Circuit Breaker - inverse time breaker. For US NEC, minimum size is $125 \%$ of motor FLA. Ratings shown are maximum
(2) Motor Circuit Protector - instantaneous trip circuit breaker. For US NEC minimum size is $125 \%$ of motor FLA. Ratings shown are maximum.
(3) Minimum protection device size is the lowest rated device that supplies maximum protection without nuisance tripping.
(4) Maximum protection device size is the highest rated device that supplies drive protection. For US NEC, minimum size is $125 \%$ of motor FLA. Ratings shown are maximum.
(5) Maximum allowable rating by US NEC. Exact size must be chosen for each installation.

## 540/650 Volt DC Input Protection Devices

| $\begin{aligned} & \hline \text { Drive } \\ & \text { Catalog } \\ & \text { Number } \\ & \hline \end{aligned}$ |  | kW <br> Rating |  | DC Input <br> Ratings |  | Output Amps |  |  | Fuse | Bussmann Style Fuse |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | ND | HD | Amps | kW | Cont. | 1 Min. | 2 Sec. |  |  |
| 540 Volt DC Input |  |  |  |  |  |  |  |  |  |  |
| 20xH261 | 9 | 132 | - | 312 | 161 | 261 | 287 | 410 | 500 | 170M6608 |
|  |  | - | 110 | 245 | 127 | 205 | 308 | 410 | 500 | 170M6608 |
| 20xH300 | 9 | 160 | - | 359 | 186 | 300 | 330 | 500 | 630 | 170M6610 |
|  |  | - | 132 | 293 | 152 | 245 | 368 | 490 | 630 | 170M6610 |
| 20xH385 | 10 | 200 | - | 460 | 238 | 385 | 424 | 600 | 700 | 170M6611 |
|  |  | - | 160 | 359 | 186 | 300 | 450 | 600 | 700 | 170M6611 |
| 20xH460 | 10 | 250 | - | 550 | 284 | 460 | 506 | 770 | 900 | 170M6613 |
|  |  | - | 200 | 460 | 238 | 385 | 578 | 770 | 900 | 170M6613 |
| 20xH500 | 10 | 250 | - | 598 | 309 | 500 | 550 | 750 | 1000 | 170M6614 |
|  |  | - | 200 | 502 | 260 | 420 | 630 | 840 | 1000 | 170M6614 |
| 650 Volt DC Input |  |  |  |  |  |  |  |  |  |  |
| 20xJ261 | 9 | 200 | - | 299 | 186 | 261 | 287 | 410 | 500 | 170M6608 |
|  |  | - | 150 | 235 | 146 | 205 | 308 | 410 | 500 | 170M6608 |
| 20xJ300 | 9 | 250 | - | 343 | 213 | 300 | 330 | 500 | 630 | 170M6610 |
|  |  | - | 200 | 281 | 174 | 245 | 368 | 490 | 630 | 170M6610 |
| 20xJ385 | 10 | 300 | - | 441 | 274 | 385 | 424 | 600 | 700 | 170M6611 |
|  |  | - | 250 | 343 | 213 | 300 | 450 | 600 | 700 | 170M6611 |
| 20xJ460 | 10 | 350 | - | 527 | 327 | 460 | 506 | 770 | 900 | 170M6613 |
|  |  | - | 300 | 441 | 274 | 385 | 578 | 770 | 900 | 170M6613 |
| 20xJ500 | 10 | 450 | - | 572 | 356 | 500 | 550 | 750 | 1000 | 170M6614 |
|  |  | - | 350 | 481 | 299 | 420 | 630 | 840 | 1000 | 170M6614 |

## Parameter List

| Parameter Name | Number | Group |
| :---: | :---: | :---: |
| Accel Mask | 281 | Masks/Owners |
| Accel Owner | 293 | Masks/Owners |
| Accel Time X | 140, 141 | Ramp Rates |
| Alarm Clear | 261 | Alarms |
| Alarm Config 1 | 259 | Alarms |
| Alarm X @ Fault | 229, 230 | Diagnostics |
| Alarm X Code | 262-269 | Alarms |
| Analog In X Hi | 322, 325 | Analog Inputs |
| Analog In X Lo | 323, 326 | Analog Inputs |
| Analog In X Loss | 324,327 | Analog Inputs |
| Analog In1 Value | 016 | Metering |
| Analog In2 Value | 017 | Metering |
| Analog OutX Hi | 343, 346 | Analog Outputs |
| Analog OutX Lo | 344,347 | Analog Outputs |
| Analog OutX Sel | 342, 345 | Analog Outputs |
| Anlg In Contig | 320 | Analog Inputs |
| Anlg In Sqr Root | 321 | Analog Inputs |
| Anlg Out Absolut | 341 | Analog Outputs |
| Anlg Out Contig | 340 | Analog Outputs |
| Anlg OutX Scale | 354, 355 | Analog Outputs |
| Anlg OutX Setpt | 377, 378 | Analog Outputs |
| Auto Rstrt Delay | 175 | Restart Modes |
| Auto Rstrt Tries | 174 | Restart Modes |
| Autotune | 061 | Torq Attributes |
| Break Frequency | 072 | Volts per Hertz |
| Break Voltage | 071 | Volts per Hertz |
| Bus Reg Kd | 165 | Stop/Brake Modes |
| Bus Reg Ki | 160 | Stop/Brake Modes |
| Bus Reg Kp | 164 | Stop/Brake Modes |
| Bus Reg Mode X | 161, 162 | Stop/Brake Modes |
| Commanded Speed | 002 | Metering |
| Control SW Ver | 029 | Drive Data |
| Current Lmt Gain | 149 | Load Limits |
| Current Lmt Sel | 147 | Load Limits |
| Current Lmt Val | 148 | Load Limits |
| Data In XX | 300-307 | Datalinks |
| Data Out XX | 310-317 | Datalinks |
| DB Resistor Type | 163 | Stop/Brake Modes |
| DC Brake Level | 158 | Stop/Brake Modes |
| DC Brake Time | 159 | Stop/Brake Modes |
| DC Brk Lvi Sel | 157 | Stop/Brake Modes |
| DC Bus Memory | 013 | Metering |
| DC Bus Voltage | 012 | Metering |
| Decel Mask | 282 | Masks/Owners |
| Decel Owner | 294 | Masks/Owners |
| Decel Time X | 142, 143 | Ramp Rates |
| Dig In Status | 216 | Diagnostics |
| Dig Out Setpt | 379 | Digital Outputs |
| Dig Out Status | 217 | Diagnostics |
| Dig OutX Level | 381, 385, 389 | Digital Outputs |
| Dig Out X Offime | 383, 387, 391 | Digital Outputs |
| Dig OutX OnTime | 382, 386, 390 | Digital Outputs |
| Digital InX Sel | 361-366 | Digital Inputs |
| Digital OutX Sel | 380, 384, 388 | Digital Outputs |
| Direction Mask | 279 | Masks/Owners |
| Direction Mode | 190 | Direction Config |
| Direction Owner | 291 | Masks/Owners |
| DPI Port Sel | 274 | Comm Control |
| DPI Port Value | 275 | Comm Control |
| Drive Alarm X | 211, 212 | Diagnostics |
| Drive Checksum | 203 | Drive Memory |
| Drive Logic Rsit | 271 | Comm Control |
| Drive Ramp Rslt | 273 | Comm Control |
| Drive Ref Rstt | 272 | Comm Control |
| Drive Status X | 209, 210 | Diagnostics |
| Drive Temp | 218 | Diagnostics |
| Droop RPM @ FLA | 152 | Load Limits |
| Elapsed MWh | 009 | Metering |
| Elapsed Run Time | 010 | Metering |
| Fault 1 Code | 243 | Faults |
| Fault 1 Time | 244 | Faults |


| Parameter Name | Number | Group |
| :---: | :---: | :---: |
| Fault 2 Code | 245 | Faults |
| Fault 2 Time | 246 | Faults |
| Fault 3 Code | 247 | Faults |
| Fault 3 Time | 248 | Faults |
| Fault 4 Code | 249 | Faults |
| Fault 4 Time | 250 | Faults |
| Fault 5 Code | 251 | Faults |
| Fault 5 Time | 252 | Faults |
| Fault 6 Code | 253 | Faults |
| Fault 6 Time | 254 | Faults |
| Fault 7 Code | 255 | Faults |
| Fault 7 Time | 256 | Faults |
| Fault 8 Code | 257 | Faults |
| Fault 8 Time | 258 | Faults |
| Fault Amps | 225 | Diagnostics |
| Fault Bus Volts | 226 | Diagnostics |
| Fault Clear | 240 | Faults |
| Fault Clear Mode | 241 | Faults |
| Fault Clr Mask | 283 | Masks/Owners |
| Fault Clr Owner | 295 | Masks/Owners |
| Fault Config 1 | 238 | Faults |
| Fault Frequency | 224 | Diagnostics |
| Feedback Select | 080 | Spd Mode/Limits |
| Flux Current | 005 | Metering |
| Flux Current Ref | 063 | Torq Attributes |
| Flux Up Mode | 057 | Torq Attributes |
| Flux Up Time | 058 | Torq Attributes |
| Flying Start En | 169 | Restart Modes |
| IR Voltage Drop | 062 | Torq Attributes |
| Ixo Voltage Drop | 064 | Torq Attributes |
| Jog Mask | 278 | Masks/Owners |
| Jog Owner | 290 | Masks/Owners |
| Jog Speed 1 | 100 | Discrete Speeds |
| Jog Speed 2 | 108 | Discrete Speeds |
| Language | 201 | Drive Memory |
| Last Stop Source | 215 | Diagnostics |
| Load Frm Usr Set | 198 | Drive Memory |
| Local Mask | 285 | Masks/Owners |
| Local Owner | 297 | Masks/Owners |
| Logic Mask | 276 | Masks/Owners |
| Man Ref Preload | 193 | HIM Ref Config |
| Maximum Freq | 055 | Torq Attributes |
| Maximum Speed | 082 | Spd Mode/Limits |
| Minimum Speed | 081 | Spd Mode/Limits |
| MOP Mask | 284 | Masks/Owners |
| MOP Owner | 296 | Masks/Owners |
| MOP Rate | 195 | MOP Config |
| MOP Reference | 011 | Metering |
| Motor Cntl Sel | 053 | Torq Attributes |
| Motor NP FLA | 042 | Motor Data |
| Motor NP Hertz | 043 | Motor Data |
| Motor NP Power | 045 | Motor Data |
| Motor NP RPM | 044 | Motor Data |
| Motor NP Volts | 041 | Motor Data |
| Motor OL Count | 220 | Diagnostics |
| Motor OL Factor | 048 | Motor Data |
| Motor OL Hertz | 047 | Motor Data |
| Motor Poles | 049 | Motor Data |
| Motor Type | 040 | Motor Data |
| Mtr NP Pwr Units | 046 | Motor Data |
| Output Current | 003 | Metering |
| Output Freq | 001 | Metering |
| Output Power | 007 | Metering |
| Output Powr Fctr | 008 | Metering |
| Output Voltage | 006 | Metering |
| Overspeed Limit | 083 | Spd Mode/Limits |
| Param Access LvI | 196 | Drive Memory |
| PI Configuration | 124 | Process PI |
| PI Control | 125 | Process PI |
| PI Error Meter | 137 | Process PI |
| PI Fdback Meter | 136 | Process PI |
| PIFeedback Hi | 462 | Process PI |


| Parameter Name | Number | Group |
| :---: | :---: | :---: |
| PI Feedback Lo | 463 | Process PI |
| PI Feedback Sel | 128 | Process PI |
| PI Integral Time | 129 | Process PI |
| PI Lower Limit | 131 | Process PI |
| PI Output Meter | 138 | Process PI |
| PI Preload | 133 | Process PI |
| PI Prop Gain | 130 | Process PI |
| PI Ref Meter | 135 | Process PI |
| Pl Reference Hi | 460 | Process PI |
| PI Reference Lo | 461 | Process PI |
| PI Reference Sel | 126 | Process PI |
| PI Setpoint | 127 | Process PI |
| PI Status | 134 | Process PI |
| PI Upper Limit | 132 | Process PI |
| Power Loss Volts | 186 | Power Loss |
| Power Loss Mode | 184 | Power Loss |
| Power Loss Time | 185 | Power Loss |
| Power Up Marker | 242 | Faults |
| Powerup Delay | 167 | Restart Modes |
| Preset Speed X | 101-107 | Discrete Speeds |
| PWM Frequency | 151 | Load Limits |
| Ramped Speed | 022 | Metering |
| Rated Amps | 028 | Drive Data |
| Rated kW | 026 | Drive Data |
| Rated Volts | 027 | Drive Data |
| Reference Mask | 280 | Masks/Owners |
| Reference Owner | 292 | Masks/Owners |
| Reset Meters | 200 | Drive Memory |
| Reset To Defalts | 197 | Drive Memory |
| Rev Speed Limit | 454 | Speed Regulator |
| S Curve \% | 146 | Ramp Rates |
| Save HIM Ref | 192 | HIM Ref Config |
| Save MOP Ref | 194 | MOP Config |
| Save To User Set | 199 | Drive Memory |
| Skip Freq Band | 087 | Spd Mode/Limits |
| Skip Frequency X | 084-086 | Spd Mode/Limits |
| Sleep Level | 182 | Restart Modes |
| Sleep Time | 183 | Restart Modes |
| Sleep-Wake Mode | 178 | Restart Modes |
| Sleep-Wake Ref | 179 | Restart Modes |
| Slip RPM @ FLA | 121 | Slip Comp |
| Slip RPM Meter | 123 | Slip Comp |
| Speed Feedback | 025 | Metering |
| Speed Ref Source | 213 | Diagnostics |
| Speed Ref X Hi | 091, 094 | Speed Reference |
| Speed Ref X Lo | 092, 095 | Speed Reference |
| Speed Ref X Sel | 090, 093 | Speed Reference |
| Speed Reference | 023 | Metering |
| Speed Units | 079 | Spd Mode/Limits |
| Speed/Torque Mod | 088 | Spd Mode/Limits |
| Start At PowerUp | 168 | Restart Modes |
| Start Inhibits | 214 | Diagnostics |
| Start Mask | 277 | Masks/Owners |
| Start Owner | 289 | Masks/Owners |
| Start/Acc Boost | 069 | Volts per Hertz |
| Status X @ Fault | 227, 228 | Diagnostics |
| Stop Owner | 288 | Masks/Owners |
| Stop/BRK Mode X | 155, 156 | Stop/Brake Modes |
| SV Boost Filter | 059 | Torq Attributes |
| TB Man Ref Hi | 097 | Speed Reference |
| TB Man Ref Lo | 098 | Speed Reference |
| TB Man Ref Sel | 096 | Speed Reference |
| Torque Current | 004 | Metering |
| Trim Hi | 119 | Speed Trim |
| Trim In Select | 117 | Speed Trim |
| Trim Lo | 120 | Speed Trim |
| Trim Out Select | 118 | Speed Trim |
| Wake Level | 180 | Restart Modes |
| Wake Time | 181 | Restart Modes |
| Voltage Class | 202 | Drive Memory |

Rockwell Automation is committed to maintaining and supporting Allen-Bradley drives and installations. Included in this commitment is start-up support and consultation for drive applications.

## ProtectionPlus Drive Start-Up

With ProtectionPlus Drives Start-Up Services from Rockwell Automation, users can leverage the extensive product and industry experience of Rockwell Automation technicians to quickly commission drives and reduce the time between integration and actual start-up.

ProtectionPlus Drive Start-Up Services verify drive installation to ensure proper electrical, mechanical and environmental criteria are met. This includes verification of power and I/O wiring to the drive, custom drive configuration/tuning to meet application specific requirements, and diagnosing/troubleshooting problems that occur during a standalone drive start-up. ProtectionPlus can also extend an eligible product parts warranty and add a labor warranty. For more information about ProtectionPlus Drives Services, contact your local Rockwell Automation sales office or authorized distributor, or visit: http://support.rockwellautomation.com/SupportPrograms.

PowerFlex is a registered trademark of Rockwell Automation.
DriveExplorer, DriveTools SP, DPI and PanelView are trademarks of Rockwell Automation.
ControlNet is a trademark of ControlNet International, Ltd.
DeviceNet is a trademark of the Open DeviceNet Vendor Association.

## www.rockwellautomation.com

## Corporate Headquarters

Rockwell Automation, 777 East Wisconsin Avenue, Suite 1400, Milwaukee, WI, 53202-5302 USA, Tel: (1) 414.212.5200, Fax: (1) 414.212 .5201

## Headquarters for Allen-Bradley Products, Rockwell Software Products and Global Manufacturing Solutions

Americas: Rockwell Automation, 1201 South Second Street, Milwaukee, WI 53204-2496 USA, Tel: (1) 414.382.2000, Fax: (1) 414.382 .4444
Europe/Middle East/Africa: Rockwell Automation SA/NV, Vorstlaan/Boulevard du Souverain 36, 1170 Brussels, Belgium, Tel: (32) 26630600 , Fax: (32) 26630640
Asia Pacific: Rockwell Automation, 27/F Citicorp Centre, 18 Whitfield Road, Causeway Bay, Hong Kong, Tel: (852) 2887 4788, Fax: (852) 25081846

## Headquarters for Dodge and Reliance Electric Products

Americas: Rockwell Automation, 6040 Ponders Court, Greenville, SC 29615-4617 USA, Tel: (1) 864.297.4800, Fax: (1) 864.281.2433
Europe/Middle East/Africa: Rockwell Automation, Brühlstraße 22, D-74834 Elztal-Dallau, Germany, Tel: (49) 6261 9410, Fax: (49) 626117741
Asia Pacific: Rockwell Automation, 55 Newton Road, \#11-01/02 Revenue House, Singapore 307987, Tel: (65) 6356-9077, Fax: (65) 6356-9011

## U.S. Allen-Bradley Drives Technical Support

Tel: (1) 262.512.8176, Fax: (1) 262.512.2222, Email: support@drives.ra.rockwell.com, Online: www.ab.com/support/abdrives


[^0]:    (1) Refer to the Installation Manual for important bipolar wiring information.
    (2) Important: Programming inputs for 2 wire control deactivates all HIM Start buttons.

